

Joint Research Activities JRA1 / JRA 2

Achievements

*Gerrit Meinecke
MARUM*

June 13th, 2013 - Brussels

Software

Hardware



JRA 1



JRA 2

Ifremer
CSIC
CNR
OGS
MPI
MUMM
IOPAS
GeoEcoMar
MARIS

AWI
Ifremer
MARUM
MPI



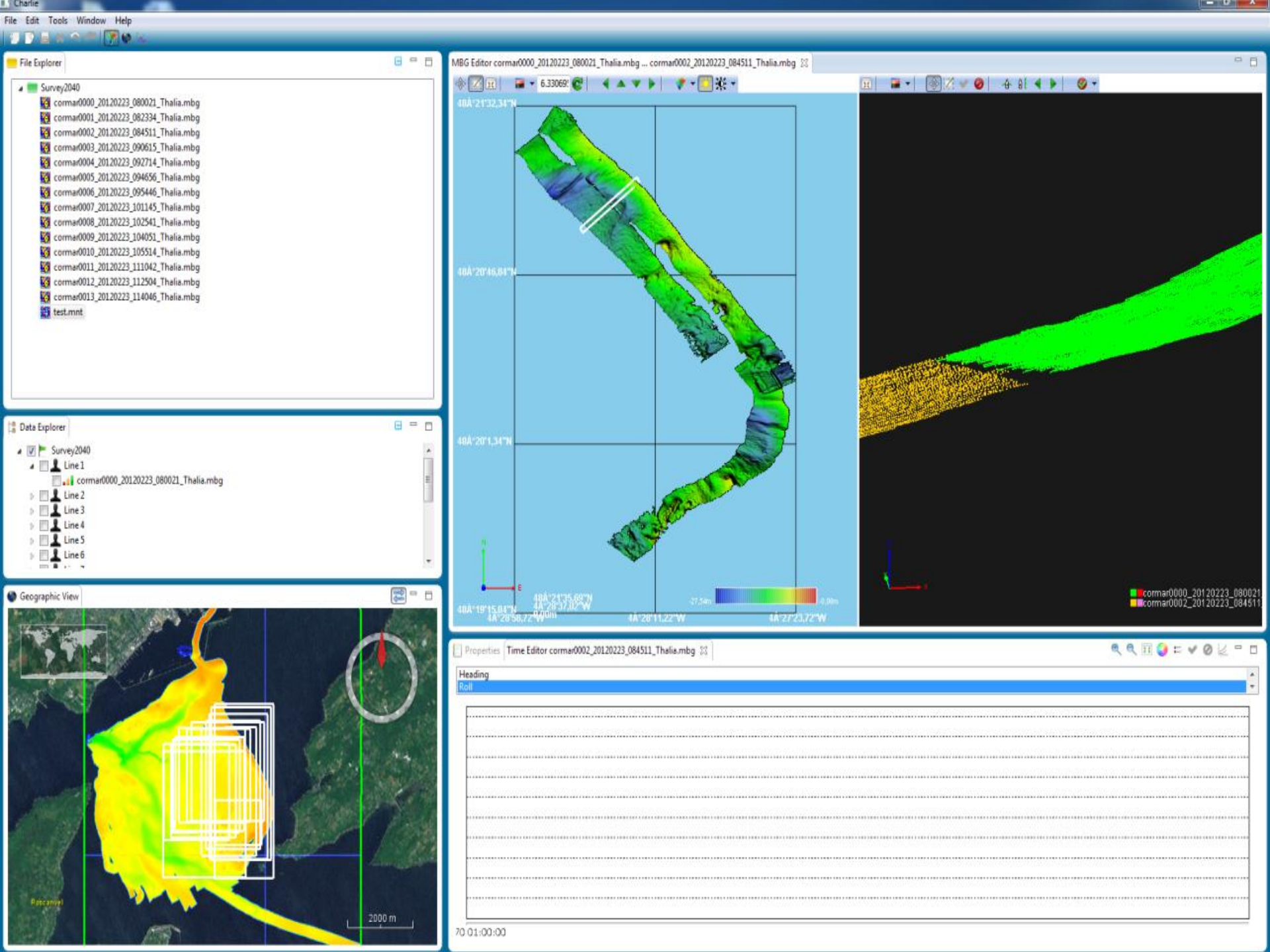
JRA 1

Goal:

Development of “Up to date” software to facilitate trans-national access

◀ ▶

[illegible]



CDIfusion and Video software

Development of a database and web based tools for the acquisition, management combined analysis of large scale genomic and contextual oceanographic data

The goal of the software is:

- to enhance the retrieval of data from database
Web service Megx.net
- to add contextual information into database –
CDiFusion
- to review and to annotate photos and video –
Video Platform

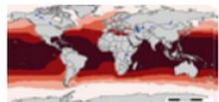


Welcome to megx.net

Megx.net allows access to integrated environmental and (meta)genomic data intended for use in marine microbial ecology

See our [Video Tutorial](#) for a guided introduction!

By integrating genomic, metagenomic and ribosomal RNA data with primary environmental data and curated metadata, we aim to offer researchers new analytical perspectives in marine ecological genomics.



mapserver

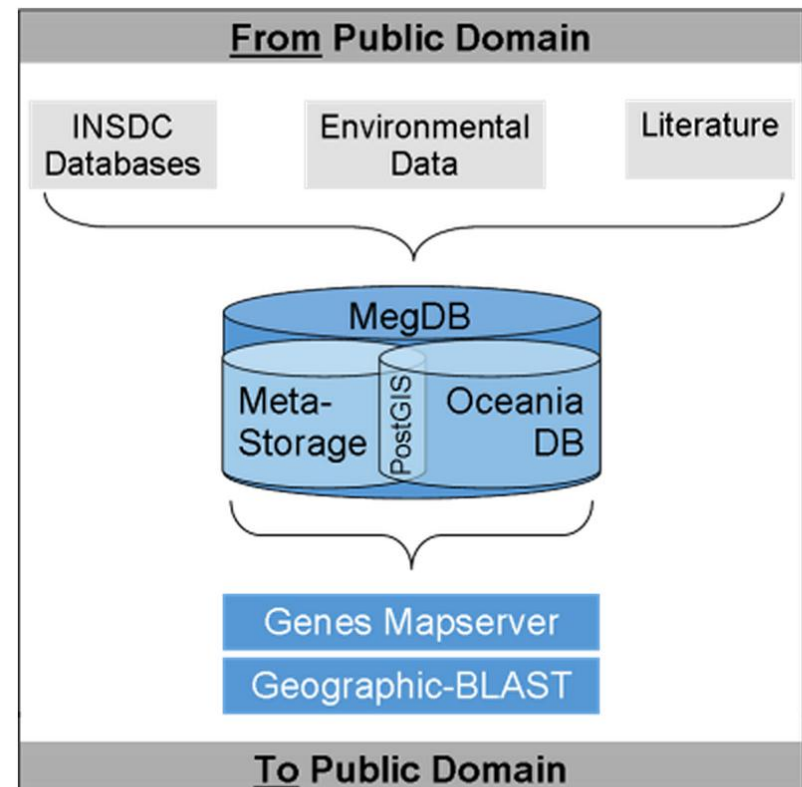
View georeferenced sampling sites in their environmental context...

GeoBLAST

BLAST your sequences against georeferenced (meta)genomes and rRNA studies to view their global distribution...

EnvO-lite

Browse genome projects classified according to sampling environment...



Categories

- Marine Biology
- Marine Geology
- Scientific Instruments
- Marine Chemistry
- Marine Physics
- Trash
- Beauty of Deep Sea

Annotations

chimney (at 3s)

crab (at 5s)

shrimp (at 12s)

shimmering water (at 263s)

shimmering water (at 293s)

marker (at 365s)

marker 3 (at 369s)

bubbling site (at 847s)

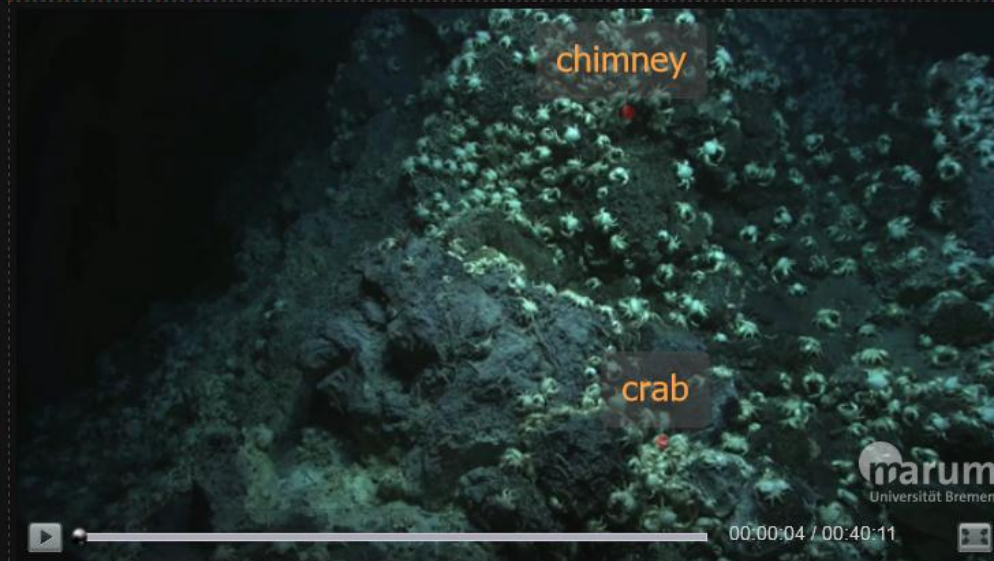
bubble box (at 1525s)

Filter

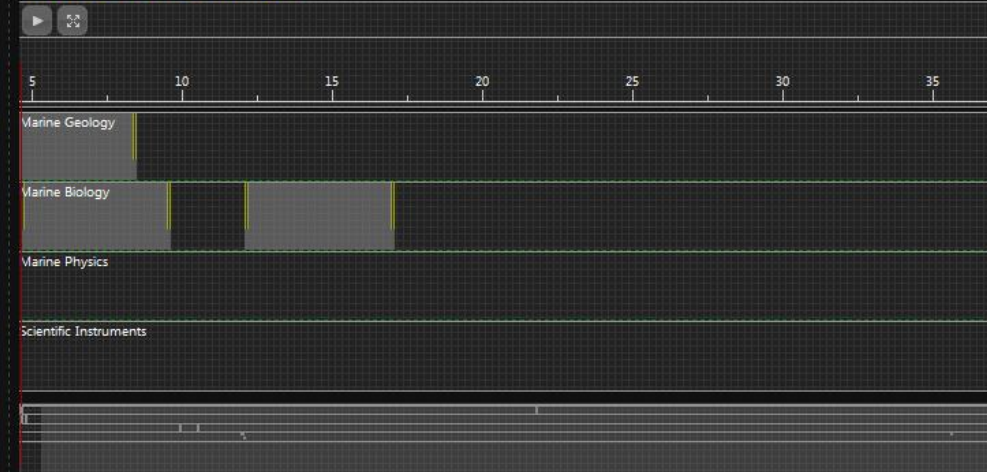
Video Time

No sequences.

dive205_HD1_01



Annotations Timeline



Video Info

Name: dive205_HD1_01

Description: SO196

Duration: 00:40:11.64

Date Uploaded: 21/05/2013 12:00:00

Date Of Filming: 11/11/1111

Search Videos

Geo Search

Click on the map to get the values!

Longitude:
 Latitude:

Radius(KM):

Time Range Filter

Time Range:

Start:
 End:

Keyword

Keyword:

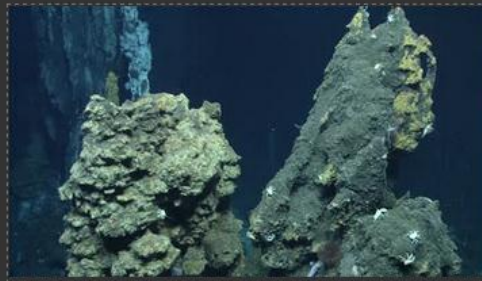
[Clear search](#)

[Search](#)



Video Search Results

Showing videos **1 - 5** of total **333**



dive312 HD1 01

SO216

Filmed by: x

Date Of Filming: 11/11/1111

Duration: 00:00:47.34

Uploaded Date: 07/06/2013 12:00:00

Video GEO Location:

Research area: x

Longitude: 43.086415516931

Latitude: 46.346331399209

Total annotations: 4

Top 10 annotations: [ray (1), shrimp (1), shimmering water (1), shark (1)]



dive312 HD1 02

SO216

Filmed by: x

Date Of Filming: 11/11/1111

JRA 2

Goal:

**Development of “scientific payloads”
shareable among European
underwater platforms**

Interoperable tools

BGC

Bio-Geochemical Module

ICASP

in-situ Sampling / Analyzing tool

3D-HDTV

High-End Camera System

CMPT

Common Mission Planning Tool



BGC – Modules MPIMM

Prototype for Sensor measurements on different underwater platforms for
biogeochemical investigations in various ecosystems

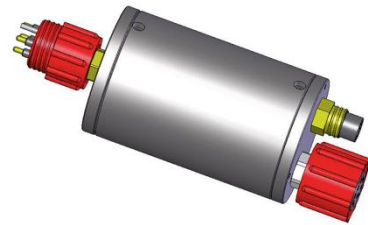


BGC-Modules: Modular system

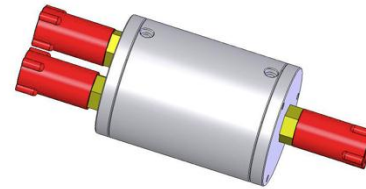
toolbox



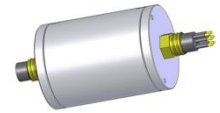
Sensor-Module
13 chemical parameter



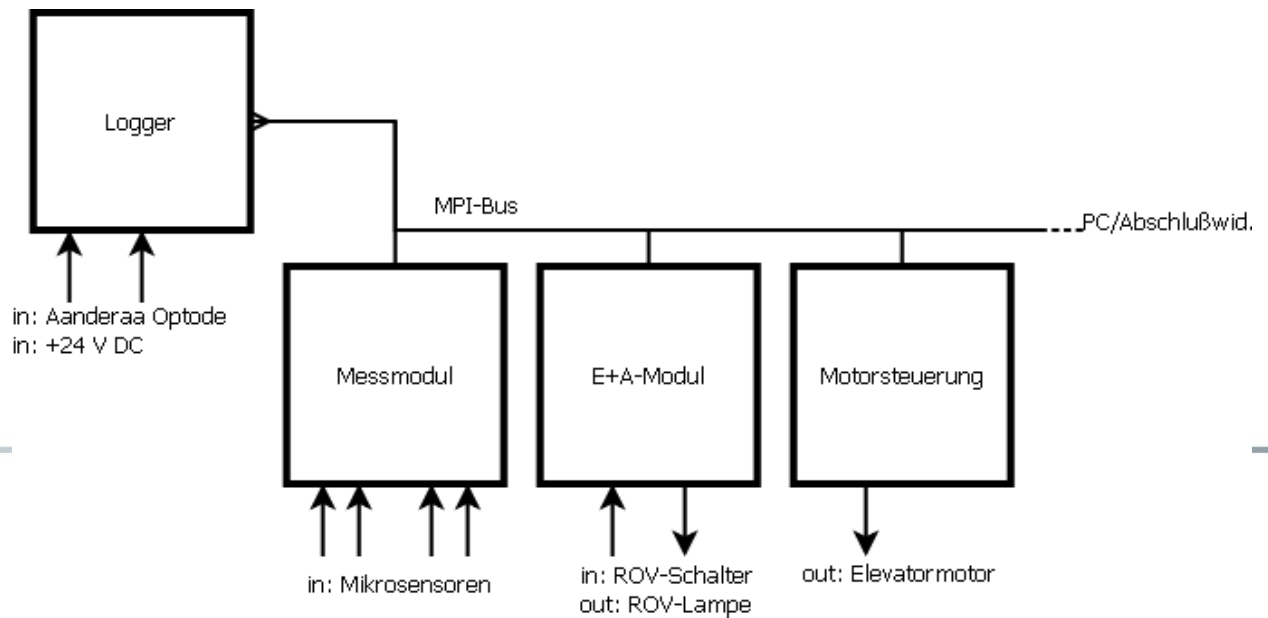
Logger-Module

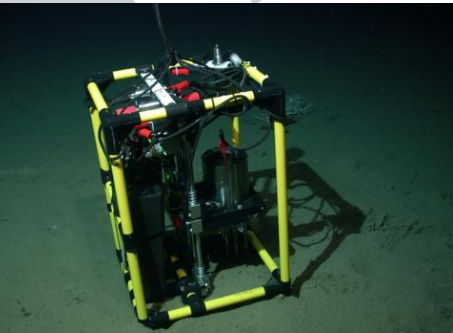


ROV-Switch/LED
-Module



Motor-Module

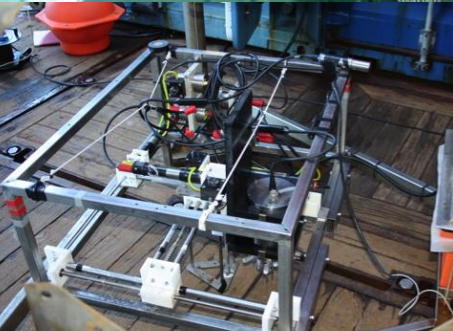




ROV-System:
Micro-Profiler
(autonomous mode)



ROV-System:
Handheld
(autonomous or
real-time mode)



Lander-System:
XYZ-Profiler
(autonomous mode)

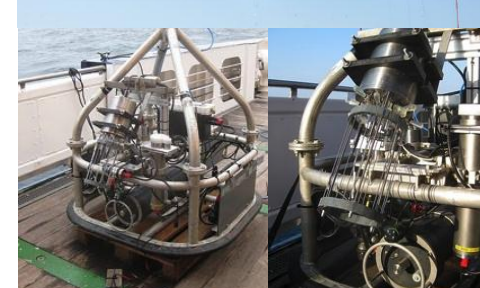


AUV-System:
Sensor-System
(autonomous mode)

Crawler-System:
Micro-Profiler
(autonomous or
real-time mode)



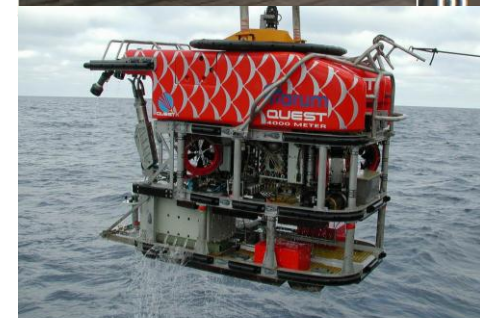
Meduda-System:
Handheld
(autonomous or
real-time mode)



OFOS-System:
XYZ-Profiler



ROV-System:
Sensor-System
(real-time mode)



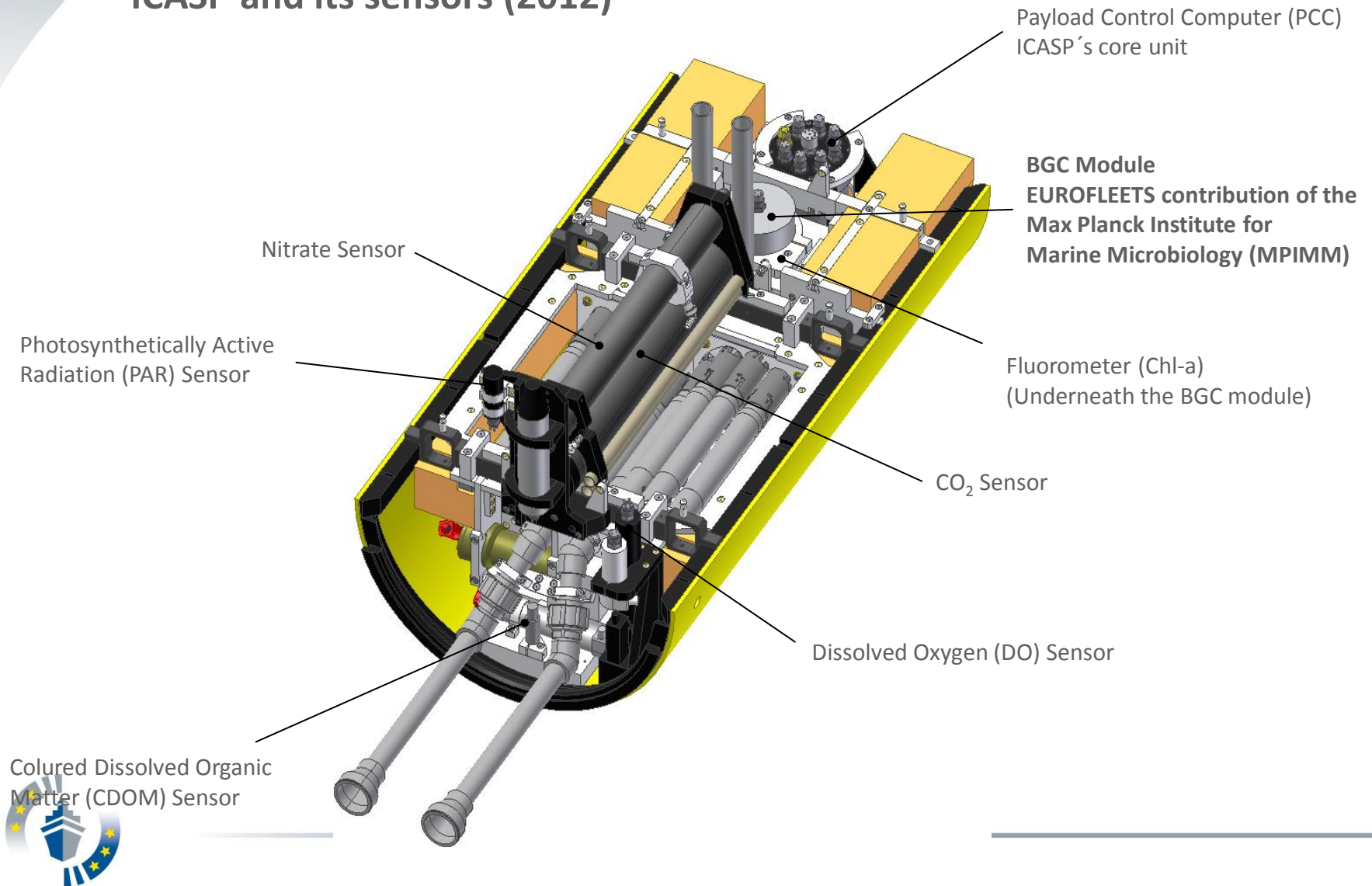
ICASP – Module

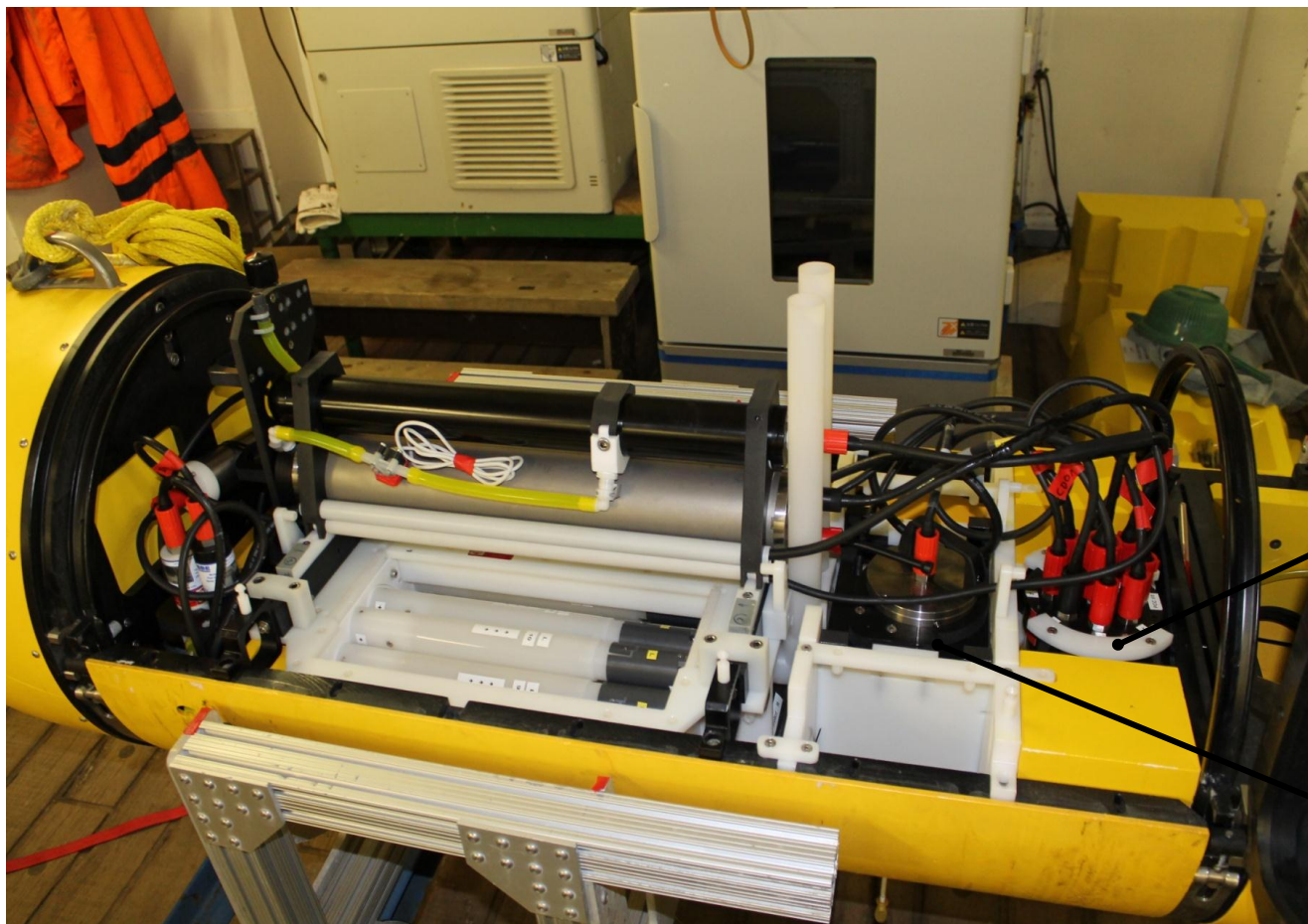
Prototype for “in-situ chemical analysis and sampling payload”

(intention – operable on AUV's)



ICASP and its sensors (2012)





PCC / ICASP

BGC Module





AWI – AUV in operation with BGC



3D-HDTV Camerasystem

Prototype for an “ultra-compact high-end HD camera-system”, designed to
be used for 3-dimensional real-time video imaging
(intention – used on ROV’s or observatories)



3D HD Operational Mode:
Manipulator-mounted “3D
Inspection”

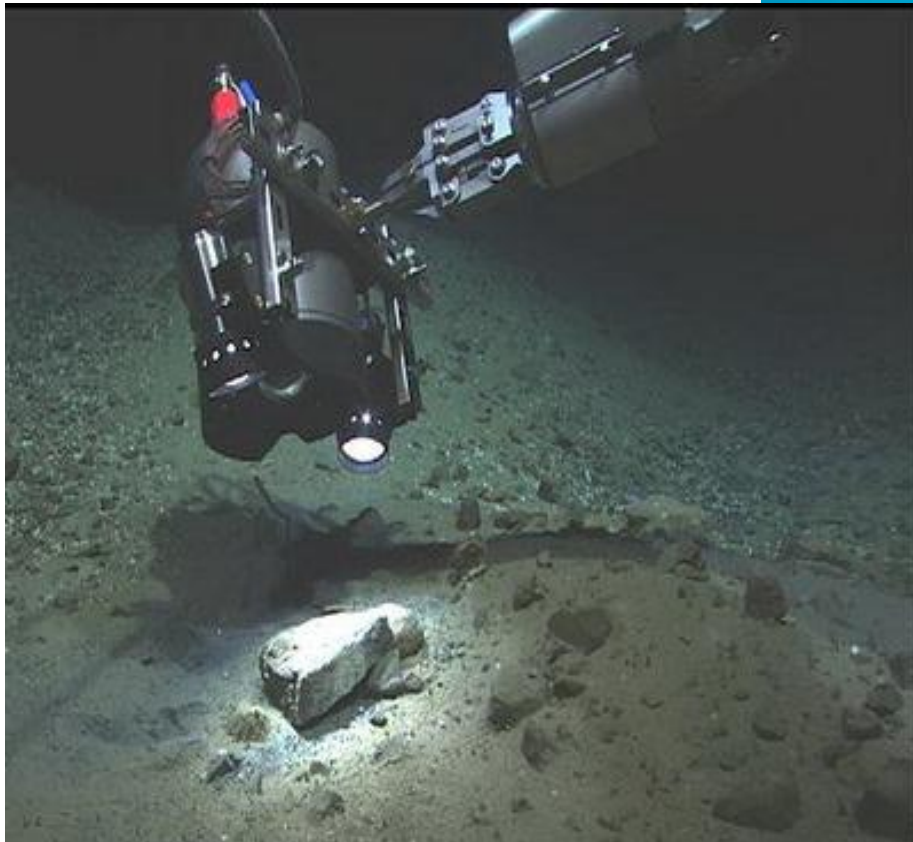


Image by Christian Lott

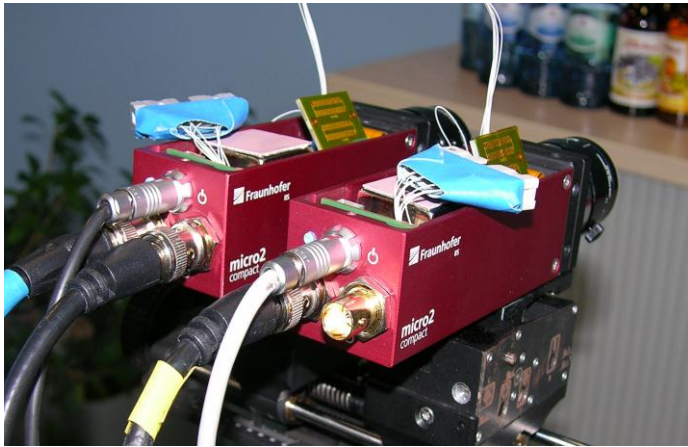


Example:
MPI- digital still “MegaCam” held
by Marum QUEST Orion
manipulator for extreme detailed
close-up photography

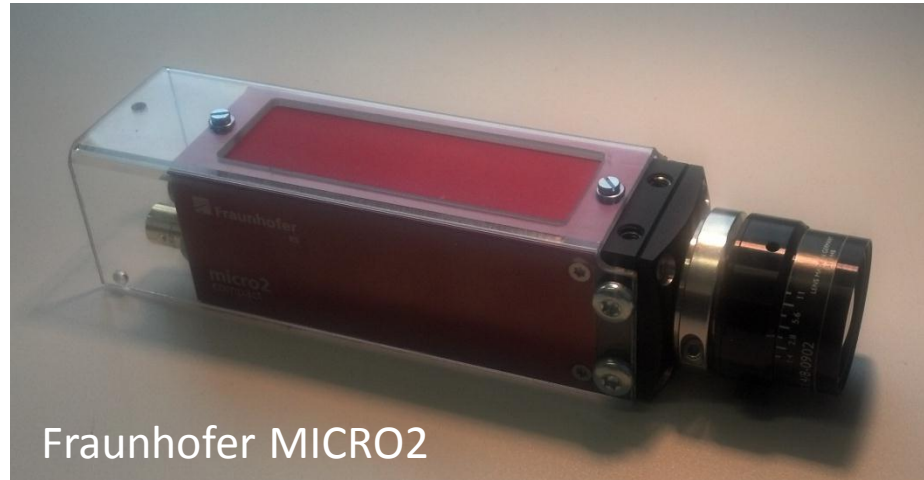
3D HDTV Camera System

Challenge:

- find a small „high-end“ HD cameras
- integrate them in „near eye distance“
- merge 2 HD signals into 1 HD stream
- transmit 1 combined 3D signal
- view 3D HD stream quality in „real time“

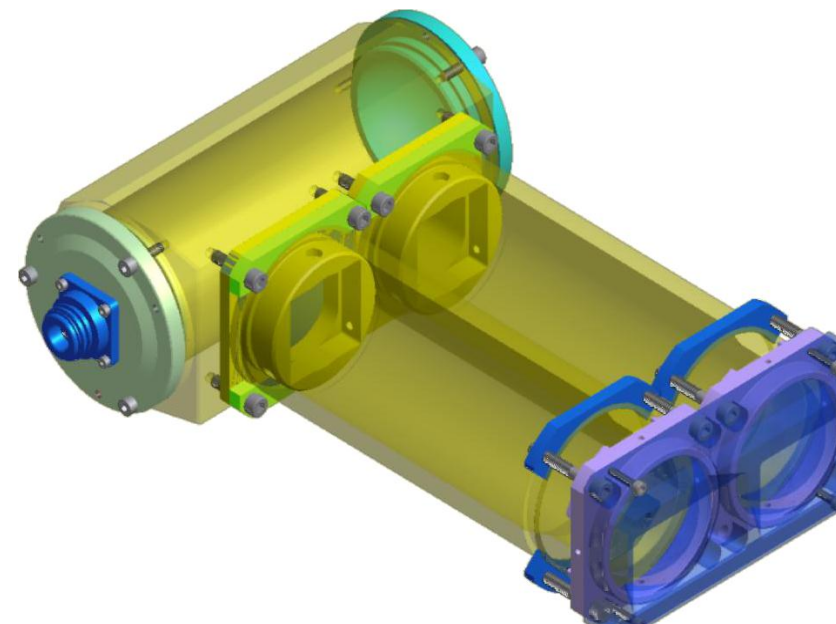
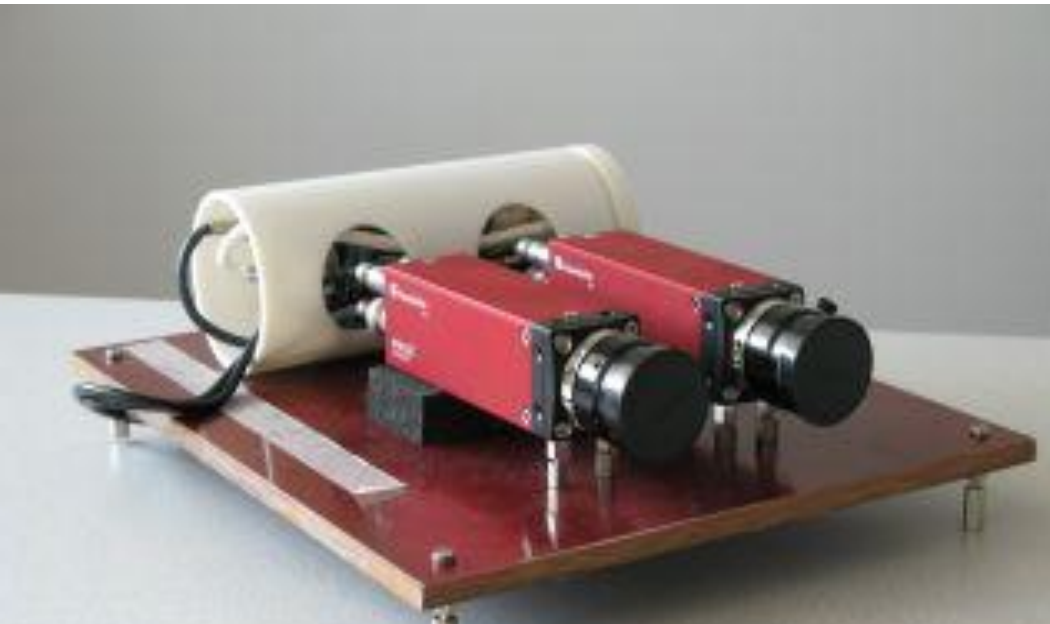
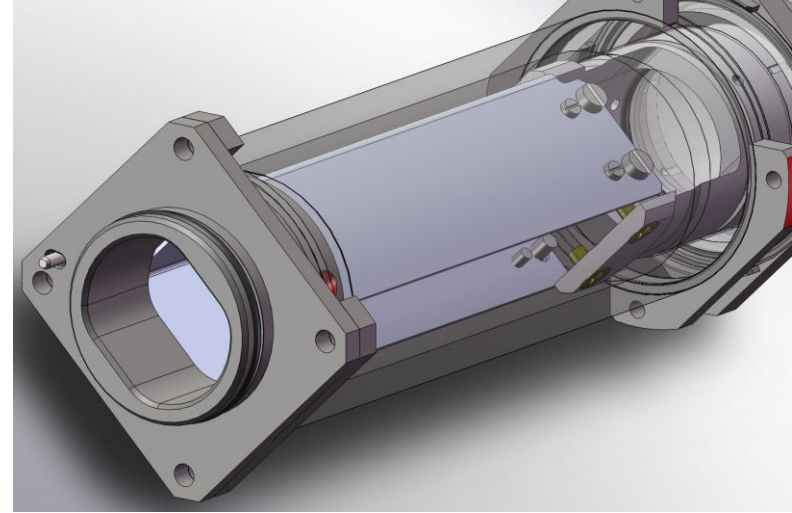
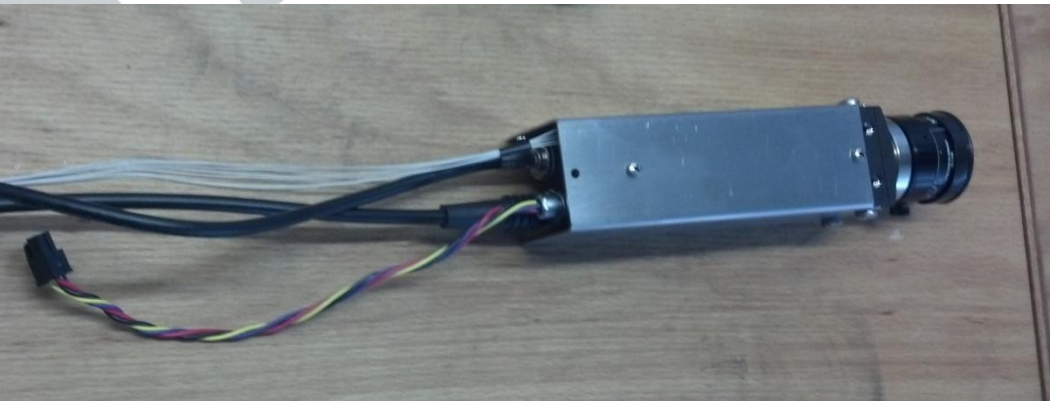


2011 – functional Prototype
at Fraunhofer IIS,
Erlangen



Fraunhofer MICRO2





3D HD Testbed with final camera version
for housing design and optical path definition

2 SME's involved for housings

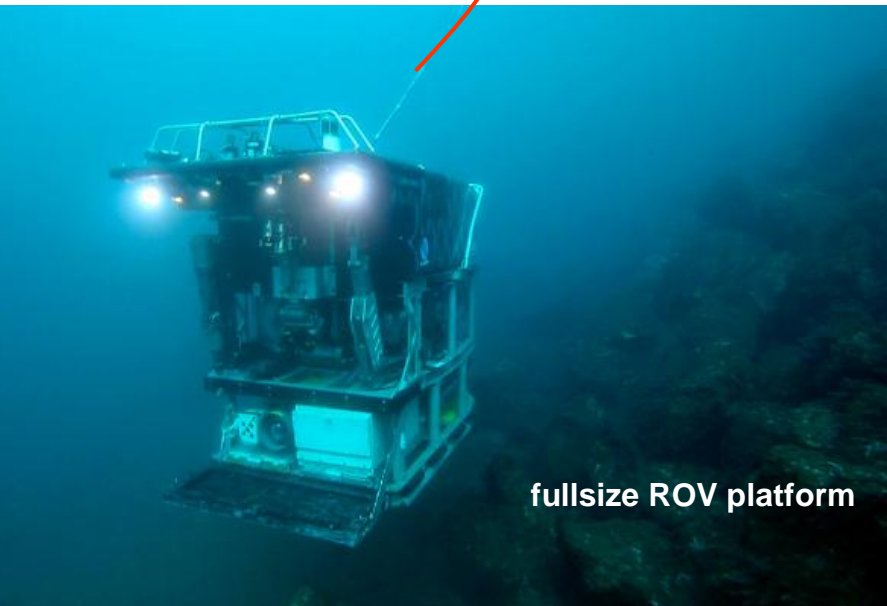


Topside Display Path 1: “Broadcast” Quality

1 x HD-SDI Videosignal



ROV IP Telemetry



fullsize ROV platform



fullsize control and display van

3D-capable Monitor:
Polarized Stereo Glasses
or 3D Projection
others possible



Topside Display Path 2: Small Systems „Easy View“

3D Display on Consumer Laptop via Bino Player
Free OpenSource Project <http://bino3d.org>



transparent
ROV IP
Telemetry



small ROV platform



Simple laptop

Common Mission Planning Tool

Prototype for a mission planning tool



Goal – a tool for mission planning

Interoperable (institute, vessel, smart-phone)

ready for **Multi-vehicle use** (AUV, Glider, ROV,)

to be used by **Scientists and Operator**

capable for **Missing planning and observation**

capable for **Data display**

capable to feed in **external** signals (video, still pictures, ..)

mission planning

MIMOSA2 [V2.3.35 24/11/2010 20:05:04] : En modification (pilote-Pilote)

PRÉPARATION Victor EssaisBase Essai01 0/0/0 Pilote En préparation

Fichier | Edition | Affichage | Campagne | Plongée | Outils | Aide | Debug

Cartographie

TOC Z2D Quadrillage

Capteurs

Victor

Nom	Valeur	Actions
Cap (dg)	2.5	
Roulis (dg)	0.45	
Tangage (dg)	-0.04	
Immersion (m)	0.0	
Altitude DVL (m)	-99.9	
Altitude alt. (m)	50.0	
Vitesse trans (m/s)	-99.9	
Vitesse long (m/s)	-99.9	
Vitesse ascen (m/s)	-99.9	
Température DVL (°C)	0	
Température CTD (°C)		

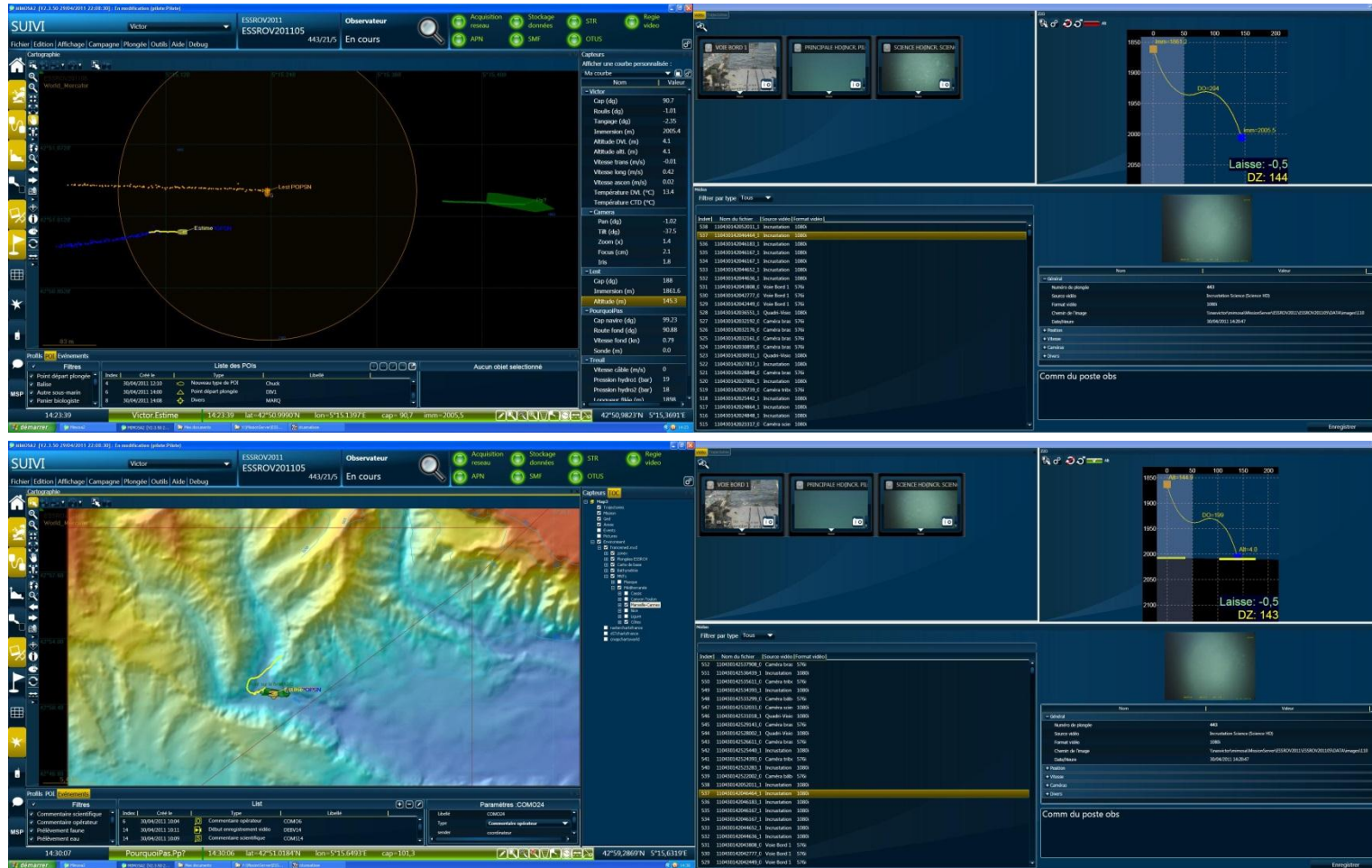
Camera

Nom	Valeur	Actions
Pan (dg)	2.4	
Tilt (dg)	-0.01	
Zoom (x)	0	
Focus (cm)	0	
Iris	0	

14:47:39 Victor.VictorNav 14:47:39 lat=43°33.1786'N lon=7°29.5910'E cap= 2,5 imm= 0,0 43°0,3340'N 6°6,2218'E



control and observation



data display

Outreach and dissemination

Search Videos

GEO Search

Click on the map to get the values!

Longitude:

33.55908035000

Latitude:

43.99219312342

Radius(KM):

2572

Time Range Filter

Time Range:

-Select Year-

Start:

dd/mm/yyyy

End:

dd/mm/yyyy

Keyword

Keyword:

Search videos by keywords

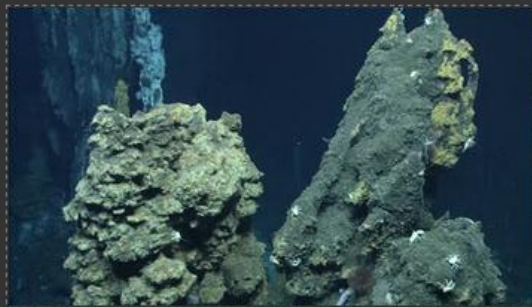
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dive312 HD1 01

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Thank you for your kind attention!

